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this book constitutes the refereed proceedings of the 5th international workshop on self organizing systems iwsos 2011 held in karlsruhe germany in february 2011 the 9 revised full

papers presented together with 1 invited paper were carefully selected from 25 initial submissions it was the 5th workshop in a series of multidisciplinary events dedicated to self organization in networked systems with main focus on communication and computer networks the papers address theoretical aspects of self organization as well as applications in communication and computer networks and robot networks

this book constitutes the proceedings of the workshops co located with the 20th international conference on practical applications of agents and multi agent systems paams 2022 held in l aquila italy in july 2022 the total of 25 full papers presented in this volume were carefully reviewed and selected from 39 submissions the papers in this volume stem from the following meetings workshop on artificial intelligence for industry ai4industry workshop on adaptive smart areas and intelligent agents assia workshop on character computing c2 workshop on deep learning applications dela workshop on decision support recommendation and persuasion in artificial intelligence derepai workshop on multi agent based applications for modern energy markets smart grids and future power systems masges

feeder transit system fts aims at arranging access to vehicles located at different depots at all demand points and transporting residents from these selected pick up stops to transportation hubs rail station and airport etc the fts transit network including a set of nodes transportation hubs bus stops demand points and depots and links between them is regarded as an effective tool to provide a better first last mile service to and from the major fixed route transit networks the first last mile access to major fixed route transit networks and connectivity of residential areas is one of the main challenges faced by public transit a well designed fts transit network shifted transport demand from individual car traffic to public transport and further enhanced urban sustainability a feasible solution to the problem is the planning design and implementation of efficient feeder transit services

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papers from a flagship conference reflect the latest developments in the field including work in such rapidly advancing areas as human robot interaction and formal methods robotics science and systems viii spans a wide spectrum of robotics bringing together contributions from researchers working on the mathematical foundations of robotics robotics applications and analysis of robotics systems this volume presents the proceedings of the eighth annual robotics science and systems rss conference held in july 2012 at the university of sydney the contributions reflect the exciting diversity of the field presenting the best the newest and the most challenging work on such topics as mechanisms kinematics dynamics and control human robot interaction and human centered systems distributed systems mobile systems and mobility manipulation field robotics medical robotics biological robotics robot perception and estimation and learning in robotic systems the conference and its proceedings reflect not only the tremendous growth of robotics as a discipline but also the desire in the robotics community for a flagship event at which the best of the research in the field can be presented

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